

**CiA 412**



*Profiles for medical devices*

Part 1: General definitions

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## HISTORY

| <b>Date</b> | <b>Changes</b>   |
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| 25.05.2003  | <i>Publication of Version 1.0 as Draft Standard Proposal</i> |
| 31.12.2005  | <i>Publication of Version 1.0 as Draft Standard</i>          |

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## 1 Scope

The CANopen profiles for medical devices includes several parts:

- Part 1 describes general definitions
- Part 2 defines the profile for automatic X-ray collimators
- Part 3 defines the profile for X-ray generators
- Part 4 defines the profile for patient tables
- Part 5 defines the profile for X-ray stands

Devices compliant to these profiles use communication techniques, which conforms to those described in the CANopen communication profile (CiA Draft Standard DS-301, /2/). In addition, medical devices and sub-systems may use communication techniques, which conform to those described in the framework for programmable CANopen Devices (CiA Draft Standard Proposal DSP-302). These specifications should be consulted in parallel to these device profile specifications.

## 2 Normative references

/1/: ISO 11898: Road vehicles – Interchange of digital information – Controller area network (CAN), November 1993.

*Note: ISO 11898 is currently under review. A new version may arise as a result of the review procedure.*

/2/: CiA DS-301 V4.02: CANopen application layer and communication profile, (February 2002).

/3/: CiA DSP-302 V3.2.1: Framework for programmable CANopen devices, (April 2003).

## 3 Acronyms and abbreviations

### CAN

Controller Area Network. Data link layer protocol for serial communication as specified in ISO 11898-1 (1999).

### COB

Communication Object, which is made of one or more CAN frames. Any information transmitted via CANopen has to be mapped into COBs.

### COB-ID

COB-Identifier. Identifies a COB uniquely in a CAN network. The identifier determines the priority of that COB in the data link layer, too.

### SDO

Service Data Object. Peer-to-peer communication with access to the Object Dictionary of a CANopen device.

### RPDO

Receive Process Data Object. Communication object of a device, which contains output data.

### TPDO

Transmit Process Data Object. Communication object of a device, which contains input data.

## 4 General operating principles

CANopen networks may not only be used for embedded communication in medical sub-systems but also to integrate medical sub-systems into medical device systems.

In medical devices, CANopen networks are used to integrate X-ray collimators, X-ray generators, patient tables, X-ray stands and other sub-systems. The sub-system communication interface is compliant to the CANopen application layer and communication profile /2/. The interface is specified in device profiles, which define the application objects as well as the default PDO communication and mapping parameter.

## 5 Physical layer definitions

The definitions given in /2/ shall apply to devices compliant to this profile. No additional specific physical layer definitions are specified.

## 6 Error handling

### 6.1 Principle

Emergency Messages shall be triggered by internal errors in the device (see /2/ for a description of emergency message handling). By default, the Emergency Messages shall contain the error field with pre-defined error numbers and additional information.

### 6.2 Error behavior

If a severe device failure is detected, the device shall automatically enter by default the pre-operational state (see /2/ CANopen NMT state machine).

If object 1029<sub>h</sub> is implemented, the device can be alternatively configured in case of a device failure to automatically enter the stopped state or remain in the current state.

Device failures shall include the following communication errors:

- Bus-off conditions on the CAN interface
- Life guarding event with the state 'occurred'
- Heartbeat event with state 'occurred'

Severe device errors may also be caused by device internal failures.

#### ***Important note for X-ray collimators:***

The X-ray collimator device profile interprets object 1029<sub>h</sub> only in relation to the behavior of the device NMT communication state machine. The behavior of the collimator finite state automaton, described in the automatic X-ray collimator device profile remains unaffected by this object.

### 6.3 Additional error code meanings

See the CANopen medical device profiles, e.g. 412-2 for automatic X-ray collimators.

## 7 Predefinitions

### 7.1 General

Either Heartbeat (recommended) or Node guarding functionality shall be supported (see /2/).

### 7.2 Predefined communication objects

#### 7.2.1 1000<sub>h</sub>: Device type

The object at index 1000<sub>h</sub> describes the type of device and its functionality. For multiple device modules the Additional information parameter shall contain FFFF<sub>h</sub> (see /2/ section 9.6.3).

#### VALUE DEFINITION

|                               |              |                            |   |
|-------------------------------|--------------|----------------------------|---|
| 31                            | 24 23        | 16 15                      | 0 |
| Specific functions            | Device class | Device profile number      |   |
| <i>Additional information</i> |              | <i>General information</i> |   |
| MSB                           |              | LSB                        |   |

*General information:*

Device profile number: 412<sub>d</sub>

*Additional information:*

Device class:

| Code                              | Function         |
|-----------------------------------|------------------|
| 0 <sub>h</sub>                    | reserved         |
| 1 <sub>h</sub>                    | X-ray collimator |
| 2 <sub>h</sub>                    | X-ray generator  |
| 3 <sub>h</sub>                    | Patient table    |
| 4 <sub>h</sub>                    | X-ray stand      |
| 5 <sub>h</sub>                    | DMS              |
| 6 <sub>h</sub> to FE <sub>h</sub> | reserved         |

Specific functions:

For X-ray collimator

| Code                              | Function   |
|-----------------------------------|--|
| 0 <sub>h</sub>                    | reserved   |
| 1 <sub>h</sub>                    | Symmetric rectangular collimator with default PDOs |
| 2 <sub>h</sub> .. FE <sub>h</sub> | <Reserved for future use>                          |

For X-ray-generator

| Code                              | Function                  |
|-----------------------------------|---------------------------|
| 0 <sub>h</sub>                    | reserved                  |
| 1 <sub>h</sub> .. FE <sub>h</sub> | <Reserved for future use> |

For patient table

| Code                              | Function                  |
|-----------------------------------|---------------------------|
| 0 <sub>h</sub>                    | reserved                  |
| 1 <sub>h</sub> .. FE <sub>h</sub> | <Reserved for future use> |

For X-ray stand

| Code                              | Function                  |
|-----------------------------------|---------------------------|
| 0 <sub>h</sub>                    | reserved                  |
| 1 <sub>h</sub> .. FE <sub>h</sub> | <Reserved for future use> |

For DMS

| Code                              | Function                  |
|-----------------------------------|---------------------------|
| 0 <sub>h</sub>                    | reserved                  |
| 1 <sub>h</sub> .. FE <sub>h</sub> | <Reserved for future use> |

### 7.2.2 1001<sub>h</sub>: Error register

The device-specific bit in the error register object may be defined in other parts of this specification as it is reserved

### 7.2.3 1029<sub>h</sub>: Error behavior

This object specifies to which state the device shall be set, when a communication error or a device-internal error is detected.

#### VALUE DEFINITION

- 0 = pre-operational (only if current state is operational)
- 1 = no state change
- 2 = stopped

#### OBJECT DESCRIPTION

| INDEX       | 1029 <sub>h</sub> |
|-------------|-------------------|
| Name        | error_behavior    |
| Object Code | Array             |
| Data Type   | Unsigned8         |
| Category    | Optional          |

**ENTRY DESCRIPTION**

|                |                                  |
|----------------|----------------------------------|
| Sub-Index      | 0 <sub>h</sub>                   |
| Description    | number_of_error_classes          |
| Access         | ro                               |
| Entry Category | Mandatory                        |
| PDO Mapping    | No                               |
| Value Range    | 1 <sub>h</sub> to 2 <sub>h</sub> |
| Default Value  | No                               |

|                |                                  |
|----------------|----------------------------------|
| Sub-Index      | 1 <sub>h</sub>                   |
| Description    | communication_error              |
| Access         | rw                               |
| Entry Category | Mandatory                        |
| PDO Mapping    | No                               |
| Value Range    | 0 <sub>h</sub> to 2 <sub>h</sub> |
| Default Value  | 1 <sub>h</sub>                   |

|                |                                  |
|----------------|----------------------------------|
| Sub-Index      | 2 <sub>h</sub>                   |
| Description    | internal_device_error            |
| Access         | rw                               |
| Entry Category | Mandatory                        |
| PDO Mapping    | No                               |
| Value Range    | 0 <sub>h</sub> to 2 <sub>h</sub> |
| Default Value  | 1 <sub>h</sub>                   |

**7.2.4 67FF<sub>n</sub>: Device type**

See /2/ section 9.6.3.