

**CiA 414**



*Device profiles for weaving machines*

Part 2: Feeders

**Version: 1.1.0**

**18 June 2007**

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## HISTORY

<b>Date</b>	<b>Changes</b>
2001-09-20	<ul style="list-style-type: none"><li>• <i>Publication of version 1.0 as draft standard proposal</i></li></ul>
2007-06-18	<ul style="list-style-type: none"><li>• <i>Publication of version 1.1 as draft standard</i><ul style="list-style-type: none"><li>○ Partly re-chaptered</li><li>○ Minor editorial corrections</li><li>○ Detailed description of PDO parameters added</li></ul></li></ul>

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## 1 Scope

Part 2 of the CANopen device profile for weaving machines specifies the CANopen interface for feeders. This device profile for feeders covers 'pre-measuring feeders' as well as 'weft feeders'.

## **2 Normative references**

The normative references given in part 1 apply for this part, too.

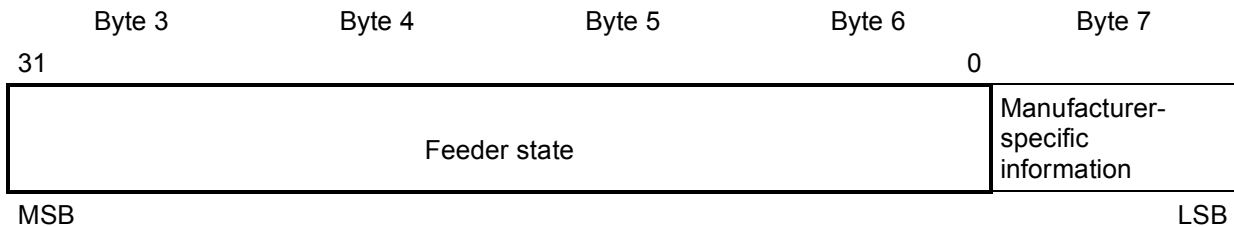
### **3 Abbreviations**

The abbreviations given in part 1 apply for this part, too.

## 4 Communication objects

### 4.1 Emergency message

An Emergency message with error code FF10h shall be transmitted when a feeder stop event occurs or when a feeder stop disappears. In this case, the manufacturing-specific error field of this Emergency message shall be structured as follows:



*Feeder state definitions:*

0 = no feeder error has occurred  
 1 = feeder error has occurred

bit 0 = state of feeder no. 1  
 bit 1 = state of feeder no. 2

to

bit 31 = state of feeder no. 32

This Emergency message does not necessarily lead to a weaving machine stop. The decision is upon responsibility of the loom controller. Emergency messages with the error code FF10h, transmitted by a feeder control box, imply that a number of feeders may be effected by errors. If feeders are not able to provide detailed failure conditions immediately after the error occurs, the Emergency message will not contain detailed failure conditions. These detailed failure conditions are available by reading to the feeder error condition object (6007h).



## 4.2 RPDO 1

This RPDO receives the pick insertion object (600Ch) from the loom controller. The pick insertion object provides the next five insertion parameters. After the occurrence of an ASS event only three pick insertion parameters may be ensured to be correct, the remaining two may still be erroneous due to the recalculation time of the loom controller. In the second PDO after an ASS event all pick insertion parameters are correct again.

Exactly one RPDO\_1 is transmitted during a logical shed, i.e. between two consecutive angle trigger signals. On one PDO loss the feeder shall indicate that in the feeder error-condition object (6007h). If more than two consecutive RPDO\_1 are lost, the feeder shall send an Emergency message and stops operation.

### OBJECT DESCRIPTION

<b>INDEX</b>	<b>1400h</b>
Name	RPDO 1 communication parameter
Object Code	Record
Data Type	PDO communication parameter record
Category	Mandatory

### ENTRY DESCRIPTION

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	02h
Default Value	02h

Sub-Index	01h
Description	COB-ID
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	4000 0200h + node-ID

Sub-Index	02h
Description	Transmission type
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	255d

The next tables define the mapping parameter.

**OBJECT DESCRIPTION**

<b>INDEX</b>	<b>1600h</b>
Name	RPDO 1 mapping parameter
Object Code	Record
Data Type	PDO mapping parameter record
Category	Mandatory

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	05h

Sub-Index	01h
Description	pick_1
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600C 01 08h

Sub-Index	02h
Description	pick_2
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600C 02 08h

Sub-Index	03h
Description	pick_3
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600C 03 08h

Sub-Index	04h
Description	pick_4
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600C 04 08h

Sub-Index	05h
Description	pick_5
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600C 05 08h

### 4.3 RPDO 2

This RPDO receives the loom status (object 600Ah) and the global weft filling parameters (object 6004h) from the loom controller.

#### OBJECT DESCRIPTION

<b>INDEX</b>	<b>1401h</b>
Name	RPDO 2 communication parameter
Object Code	Record
Data Type	PDO communication parameter record
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	2h
Default Value	2h

Sub-Index	01h
Description	COB-ID
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	4000 0300h + node-ID

Sub-Index	02h
Description	Transmission type
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	255d

The next tables define the mapping parameter.

#### OBJECT DESCRIPTION

<b>INDEX</b>	<b>1601h</b>
Name	RPDO 2 mapping parameter
Object Code	Record
Data Type	PDO mapping parameter record
Category	Mandatory

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	02h

Sub-Index	01h
Description	loom status
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600A 00 08h

Sub-Index	02h
Description	global weft filling parameter
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	6004 00 20h

#### 4.4 RPDO 3

This RPDO is optional and receives depending on the hardware features up to 8 x 8 digital outputs (object 600Dh) from the loom controller.

##### OBJECT DESCRIPTION

<b>INDEX</b>	<b>1402h</b>
Name	RPDO 3 communication parameter
Object Code	Record
Data Type	PDO communication parameter record
Category	Optional

##### ENTRY DESCRIPTION

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	02h
Default Value	02h

Sub-Index	01h
Description	COB-ID
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	4000 0400h + node-ID

Sub-Index	02h
Description	Transmission type
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	255d

The next tables define the mapping parameter.

##### OBJECT DESCRIPTION

<b>INDEX</b>	<b>1602h</b>
Name	RPDO 3 mapping parameter
Object Code	Record
Data Type	PDO mapping parameter record
Category	Conditional: Mandatory if object 1402h is implemented

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	08h

Sub-Index	01h
Description	output group 1
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600D 01 08h

Sub-Index	02h
Description	output group 2
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600D 02 08h

Sub-Index	03h
Description	output group 3
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600D 03 08h

Sub-Index	04h
Description	output group 4
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600D 04 08h

Sub-Index	05h
Description	output group 5
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600D 05 08h

Sub-Index	06h
Description	output group 6
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600D 06 08h

Sub-Index	07h
Description	output group 7
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600D 07 08h

Sub-Index	08h
Description	output group 8
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600D 08 08h



#### 4.5 RPDO 4

This RPDO is mandatory if the loom controller selected at least one trigger function (angle or brush-release or pick insertion trigger). The PDO is transmitted whenever the angle-trigger occurs or the brush-release signal changes or the pick insertion release signal changes.

##### OBJECT DESCRIPTION

<b>INDEX</b>	<b>1403h</b>
Name	RPDO 4 communication parameter
Object Code	Record
Data Type	PDO communication parameter record
Category	Conditional: mandatory, if the loom controller selected at least one trigger function

##### ENTRY DESCRIPTION

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	2h
Default Value	2h

Sub-Index	01h
Description	COB-ID
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	0000 0500h + node-ID

Sub-Index	02h
Description	Transmission type
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	255d

The next tables define the mapping parameter.

**OBJECT DESCRIPTION**

<b>INDEX</b>	<b>1603h</b>
Name	RPDO 4 mapping parameter
Object Code	Record
Data Type	PDO mapping parameter record
Category	Conditional: Mandatory if object 1403h is implemented

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	1h

Sub-Index	01h
Description	trigger signal
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	600B 00 08h

#### 4.6 TPDO 1

This TPDO transmits the feeder unwinding time object (6010h). At each winding inserted the pre-measuring feeder transmits this TPDO.

##### OBJECT DESCRIPTION

<b>INDEX</b>	<b>1800h</b>
Name	TPDO 1 communication parameter
Object Code	Record
Data Type	PDO communication parameter record
Category	Mandatory

##### ENTRY DESCRIPTION

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	2h to 5h
Default Value	Manufacturer-specific

Sub-Index	01h
Description	COB-ID
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	{C000 0180h, 4000 0180h} + node-ID

Sub-Index	02h
Description	Transmission type
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	255d

Sub-Index	03h
Description	Inhibit time
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	0d

Sub-Index	05h
Description	Event timer
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	see /CiA301/
Default Value	0d

The next tables define the mapping parameter.

#### OBJECT DESCRIPTION

<b>INDEX</b>	<b>1A00h</b>
Name	TPDO 1 mapping parameter
Object Code	Record
Data Type	PDO mapping parameter record
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Description	Highest sub-index supported
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	01h

Sub-Index	01h
Description	trigger signal
Entry Category	Mandatory
Access	constant
PDO Mapping	No
Value Range	No
Default Value	6010 00 20h

## 5 Object dictionary

### 5.1 Overview on object dictionary entries

INDEX	Name
6000h	brush_release
6001h	feeder_functions
6002h	weft_insertion_type_parameter
6003h	single_weft_filling_parameter
6004h	global_weft_filling_parameter
6005h	trigger_signal_source
6006h	angle_trigger_timeout
6007h	feeder_error_condition
6008h	fcf_error_condition
6009h	feeder_status
600Ah	loom_status
600Bh	trigger_signal
600Ch	pick_insertion
600Dh	digital_outputs
600Eh	feeder_command
600Fh	feeder_test
6010h	feeder_unwinding_time
6011h	system_feeder_number_assignment
6012h	feeder_color_assignment

### 5.2 Detailed specification of object entries

#### 5.2.1 Object 6000h: brush release

This object provides the opening delay time and the closing delay time. Both values are given in 0.1 ms/bit.

In pre-operational status, the brush release function shall be configured inside the weaving machine control for correct use in operational status. The brush release function itself, i.e. opening of the CTR/flexbrake during weft insertion to reduce the maximum yarn tension on the weft, can be provided either through the parallel function trigger signals. The brush release configuration parameters include feeder-specific delay times for the brush release function. A weaving machine that wants to use brush release shall read object 6000h from every feeder before the first start in order to be able to use brush release. The delay times specify the lead times needed by the feeder to open/close the brush after reception of the trigger signal, i.e. time by which the weaving machine shall send the trigger signal in advance so that the feeder will open/close the brush correctly. This function is only available if the respective feeder supports the brush release functionality (see object 6001h).

**OBJECT DESCRIPTION**

<b>INDEX</b>	<b>6000h</b>
Name	brush_release
Object Code	Array
Data Type	Unsigned16
Category	Conditional

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	02h
Default Value	02h

Sub-Index	01h
Description	opening_delay_time
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	Unsigned16
Default Value	00h

Sub-Index	02h
Description	closing_delay_time
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	Unsigned16
Default Value	00h

### 5.2.2 Object 6001h: feeder functions

This object provides the feeder functionality. After power-on the functions and sensors that are not supported by the feeders, are set to "not available". E.g. BR = 00 = "Brush-release not available". If they are supported they have to be set to "on" or "off". E.g. AT = 10 = "Angle-trigger monitoring off".

By writing to this object, the feeder functions are set. Only those functions and sensors that are marked as supported can be changed.

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
BR	WD	AT	r	r	r	r	r	r	YB	IKD	YQ	RD	TKS	r	r	r																
MSB																	LSB															

Name	Bit value	Function
BR	10	Brush release off
	11	Brush release on
	00	Brush release not available
WD	10	Winding direction is S
	11	Winding direction is Z
AT	10	Angle trigger monitoring off
	11	Angle trigger monitoring on
	00	Angle trigger monitoring not available
YB	10	Yarn break sensor not active
	11	Yarn break sensor active
	00	Yarn break sensor not available
IKD	10	Input knot detection sensor not active
	11	Input knot detection sensor active
	00	Input knot detection sensor not available
YQ	10	Yarn quality sensor not active
	11	Yarn quality sensor active
	00	Yarn quality sensor not available
RD	10	Rotation direction sensor not active
	11	Rotation direction sensor active
	00	Rotation direction sensor not available
TKS	10	TKS sensor not active
	11	TKS sensor active
	00	TKS sensor not available
R	00	reserved

#### OBJECT DESCRIPTION

INDEX	6001h
Name	feeder_functions
Object Code	Array
Data Type	Unsigned32
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to FEh
Default Value	No

Sub-Index	01h
Description	feeder_1
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	See definitions above
Default Value	No

Sub-Index	02h
Description	feeder_2
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	See definitions above
Default Value	No

to

Sub-Index	FEh
Description	feeder_254
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	See definitions above
Default Value	No



### 5.2.3 Object 6002h: weft insertion type parameter

This object shall be configured before processing PDOs. When this object is not configured and a PDO is received or a PDO transmission request occurs, an Emergency message shall be transmitted containing the error code FF10h and the corresponding value in the feeder error condition object (6007h) shall be set. The following values shall be used:

0h = do not process PDOs  
 1h = projectile  
 2h = rapier  
 3h = air jet  
 4h = water jet  
 5h to FF = reserved

#### OBJECT DESCRIPTION

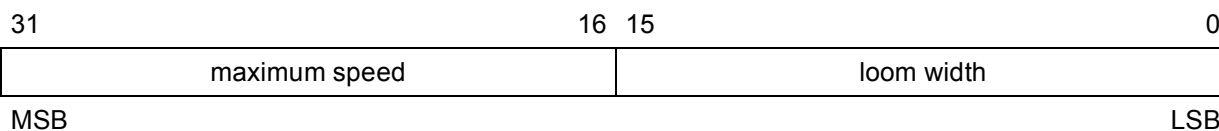
INDEX	6002h
Name	weft_insertion_type_parameter
Object Code	Variable
Data Type	Unsigned8
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Access	wo
PDO Mapping	No
Value Range	See definition above
Default Value	00h

### 5.2.4 Object 6003h: single weft filling parameter

This object contains information about the filling section of the weaving machine for a single feeder. This information is obsolete if global weft filling parameter (object 6004h) is unequal 0. This object provides information about weft filling rate and weft yarn specification (e.g. weft yarn quality, yarn type, etc.). The maximum speed is given in 1/min/bit and the loom width is given in cm/bit.



#### OBJECT DESCRIPTION

INDEX	6003h
Name	single_weft_filling_parameter
Object Code	Array
Data Type	Unsigned32
Category	Optional

#### ENTRY DESCRIPTION

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to FEh
Default Value	No

Sub-Index	01h
Description	feeder_1
Entry Category	Mandatory
Access	wo
PDO Mapping	Optional
Value Range	See definitions above
Default Value	No

Sub-Index	02h
Description	feeder_2
Entry Category	Optional
Access	wo
PDO Mapping	Optional
Value Range	See definitions above
Default Value	No

to

Sub-Index	254h
Description	feeder_254
Entry Category	Optional
Access	wo
PDO Mapping	Optional
Value Range	See definitions above
Default Value	No

### 5.2.5 Object 6004h: global weft filling parameter

This object contains information about the filling section of the weaving machine for all feeders simultaneously.

#### OBJECT DESCRIPTION

<b>INDEX</b>	<b>6004h</b>
Name	global_weft_filling_parameter
Object Code	Variable
Data Type	Unsigned32
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Access	wo
PDO Mapping	Default
Value Range	See definitions in object 6003h
Default Value	No

### 5.2.6 Object 6005h: trigger signal source

This object defines in sub-index 1, which trigger sources are supported, and in sub-index 2 which trigger sources are selected. By default in sub-index 2, "angle trigger" occurs implicitly on receiving the "pick insertion object" and the "brush-release signal" is set via CANopen network, and "pick release trigger" is not selected.

The following definition shall apply for sub-index 1:

15	12 11	8 7	4 3	0
reserved	supported pick release trigger sources	supported angle-trigger sources	supported brush- release signal sources	
MSB				LSB

Bit definitions:

0 = source is not available

1 = source is available

Bit no.	Signal/trigger	Source
00	Brush-release signal	CANopen network possible (via object 600Bh)
01		Parallel brush-release signal line possible
02		reserved
03		reserved
04	Angle-trigger	CANopen network possible (via object 600Bh)
05		Parallel angle-trigger line possible
06		reserved
07		reserved
08	Pick release trigger	CANopen network possible (via object 600Bh)
09		Parallel pick release trigger line possible
10		reserved
11		reserved
12	reserved	reserved
13	reserved	reserved
14	reserved	reserved
15	reserved	reserved

If "angle-trigger sources" results to 0 then the explicit triggering via CANopen network or via parallel line is not possible. In this case, there is an "implicit angle trigger" whenever "pick insertion object" (600Ch) is received.

If brush-release signal sources results to 0 then the brush-release function is off and the brushes are set or released or unaffected as defined in object feeder functions (6001h), section "BR".

The following definition shall apply for sub-index 2:

15	12 11	8 7	4 3	0
reserved	selected pick release trigger sources	selected angle-trigger sources	selected brush-release signal sources	
MSB				LSB

Bit definitions:

0 = source not selected

1 = source selected

Bit no.	Signal/trigger	Source
00	Brush-release signal	CANopen network
01		Parallel brush-release signal line
02		reserved
03		reserved
04	Angle-trigger	CANopen network
05		Parallel angle-trigger line
06		reserved
07		reserved
08	Pick release trigger	CANopen network
09		Parallel pick release trigger line possible
10		reserved
11		reserved
12	reserved	reserved
13	reserved	reserved
14	reserved	reserved
15	reserved	reserved

Reserved bits shall be 0.

**OBJECT DESCRIPTION**

<b>INDEX</b>	<b>6005h</b>
Name	trigger_signal_source
Object Code	Array
Data Type	Unsigned16
Category	Mandatory

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	02h
Default Value	02h

Sub-Index	01h
Description	trigger_sources_supported
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	See definitions above
Default Value	00h

Sub-Index	02h
Description	trigger_sources_selected
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	See definitions above
Default Value	01h

### 5.2.7 Object 6006h: angle trigger timeout

When the angle trigger is provided via CANopen, a timeout shall be defined in order to allow the feeder to monitor the correct synchronization between loom controller and feeder. The timeout value shall be configured in pre-operational status. The timeout value given in ms defines the maximum time allowed between two consecutive occurrences of the angle trigger signals when loom status (600Ah) has a value of 1 ("normal running"). When there is a value of 0h, the feeder is not allowed to process PDOs. When this object is not configured and a PDO is received or a PDO transmission request occurs, an Emergency message shall be transmitted containing the error code FF10h and the corresponding value in the feeder error condition object (6007h) respectively feeder-control box error condition object (6008h) shall be set.

#### OBJECT DESCRIPTION

<b>INDEX</b>	<b>6006h</b>
Name	angle_trigger_timeout
Object Code	Variable
Data Type	Unsigned16
Category	Conditional

#### ENTRY DESCRIPTION

Sub-Index	00h
Access	rw
PDO Mapping	No
Value Range	Unsigned16
Default Value	00h

### 5.2.8 Object 6007h: feeder error condition

This object provides detailed information on feeder errors, which have been indicated by an Emergency message with the error code FF10h. If more than one error occurs at a feeder, the first error is considered as main error. The following value definitions shall apply:

#### VALUE DEFINITION

VALUE	DESCRIPTION
00h	No error
01h	No settings available in EEPROM
02h	On/off switch in off-state
03h	Weaving machine parameter missing
04h	Yarn is broken
05h	Pre-winder is running empty
06h	Temperature too high
07h	Motor voltage not okay
08h	No communication with EEPROM
09h	Rotation not possible
0Ah	Filling up failed
0Bh	Color information missing
0Ch	Angle trigger signal missing
0Dh	TKS event
0Eh	Knot detected
0Fh	General error
10h to FFh	Reserved

#### OBJECT DESCRIPTION

<b>INDEX</b>	<b>6007h</b>
Name	feeder_error_condition
Object Code	Array
Data Type	Unsigned8
Category	Optional

#### ENTRY DESCRIPTION

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to FEh
Default Value	No

Sub-Index	01h
Description	feeder_1
Entry Category	Mandatory



Access	ro
PDO Mapping	No
Value Range	See definitions above
Default Value	No

Sub-Index	02h
Description	feeder_2
Entry Category	Optional
Access	ro
PDO Mapping	No
Value Range	See definitions above
Default Value	No

to

Sub-Index	FEh
Description	feeder_254
Entry Category	Optional
Access	ro
PDO Mapping	No
Value Range	See definitions above
Default Value	No

### 5.2.9 Object 6008h: Feeder control box error condition

This object provides detailed information on feeder control box errors, which have been indicated by an Emergency message. The following value definitions shall apply:

00h = no error  
 01h = no settings available in EEPROM  
 02h = *reserved*  
 03h = weaving machine parameters missing  
 04h = *reserved*  
 05h = *reserved*  
 06h = temperature too high  
 07h = motor voltage not okay  
 08h = no communication with EEPROM  
 09h = *reserved*  
 0Ah = *reserved*  
 0Bh = color information missing  
 0Ch = angle trigger signal missing  
 0Dh = *reserved*  
 0Eh = *reserved*  
 0Fh = general Error  
 10h to FF = *reserved*

#### OBJECT DESCRIPTION

INDEX	6008h
Name	fcg_error_condition
Object Code	Variable
Data Type	Unsigned8
Category	Optional

#### ENTRY DESCRIPTION

Sub-Index	00h
Access	ro
PDO Mapping	No
Value Range	See definitions above
Default Value	00h

**5.2.10 Object 6009h: feeder status**

This object provides detailed information about the internal status of the feeder sub-system. The following value definition shall apply:

0h = operational mode  
 1h = positioning mode  
 2h = filling up to maximum sensor  
 3h = PCAT test mode  
 4h = non-operational mode  
 5h = not present  
 6h = initializing mode  
 7h = error mode  
 8h to FEh = reserved

**OBJECT DESCRIPTION**

<b>INDEX</b>	<b>6009h</b>
Name	feeder_status
Object Code	Array
Data Type	Unsigned8
Category	Mandatory

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to FEh
Default Value	No

Sub-Index	01h
Description	feeder_1
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	See definitions above
Default Value	No

Sub-Index	02h
Description	feeder_2
Entry Category	Optional
Access	ro
PDO Mapping	No
Value Range	See definitions above
Default Value	No

to

Sub-Index	FEh
Description	feeder_254
Entry Category	Optional
Access	Ro
PDO Mapping	No
Value Range	See definitions above
Default Value	No

### 5.2.11 Object 600Ah: loom status

The loom controller provides its status information by PDO service. The following value definitions shall apply:

0h = stop

1h = start advice (loom speed value is sent in the very same PDO, loom-status changed to "normal running")

2h = new speed only (no change of loom status)

3h = slow motion forward

4h = slow motion backward

5h to FEh = reserved

#### OBJECT DESCRIPTION

INDEX	600Ah
Name	loom_status
Object Code	Variable
Data Type	Unsigned8
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Access	wo
PDO Mapping	Default
Value Range	See definitions above
Default Value	00h

### 5.2.12 Object 600Bh: trigger signal

This object defines the loom's angle triggers, pick release triggers and brush-release signals, when those are defined within objects 6001h (feeder functions) and 6005h (trigger signal source). The loom controller transmits this object by PDO service. The following value definitions shall apply:

00h = no signal

01h = angle trigger

02h = pick release trigger

03h = brush signal 'do not release'

04h = brush signal 'do release'

05h = to FEh = reserved for future triggers

The angle and pick release trigger shall occur only once per insertion pick: \_\_\_\_|\_\_\_\_\_|\_\_\_\_

The brush-signal may change 0, 2 or 4 times per pick: \_\_\_\_-\_\_\_\_-\_\_\_\_-\_\_\_\_-\_\_\_\_

#### OBJECT DESCRIPTION

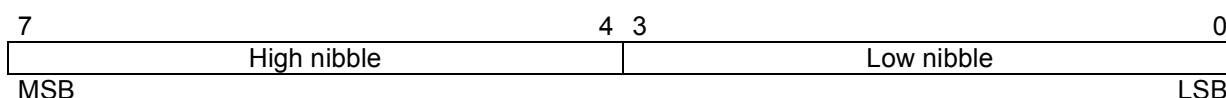
INDEX	600Bh
Name	trigger_signal
Object Code	Variable
Data Type	Unsigned8
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Access	wo
PDO Mapping	Default
Value Range	See definitions above
Default Value	No

### 5.2.13 Object 600Ch: pick insertion

This object provides color information for the next consecutive five picks for pre-measuring feeders. The feeder may use the color information to calculate acceleration and retardation ramps and therefore keep the stress on the web as low as possible. The following value definitions shall apply:



High nibble	Low nibble	Pick insertion
0h	0h	Empty pick
0h	1h to Fh	Single pick insertion with color 1 to 15
1h	0h	Single pick insertion with color 16
1h to Fh	1h to Fh	Double pick insertion with color 1 to 15 and color 1 to 15
1h	1h	Triple pick insertion with color 1, 3 and 5
2h	2h	Triple pick insertion with color 2, 4 and 6
3h	3h	Triple pick insertion with color 3, 5 and 7
4h	4h	Triple pick insertion with color 4, 6 and 8
5h	5h	Triple pick insertion with color 5, 7 and 9
6h	6h	Triple pick insertion with color 6, 8 and 10
7h	7h	Triple pick insertion with color 7, 9 and 11
8h	8h	Triple pick insertion with color 8, 10 and 12
9h	9h	Triple pick insertion with color 9, 11 and 13
Ah	Ah	Triple pick insertion with color 10, 12 and 14
Bh	Bh	Triple pick insertion with color 11, 13 and 15
Ch	Ch	Triple pick insertion with color 12, 14, and 16
Dh	Dh	reserved
Eh	Eh	reserved
Fh	Fh	reserved

In order to have some free High/Low-nibble combinations for future use, there is the following restriction:

$$\text{HighNibble} = 0 \text{ or } \text{HighNibble} \geq \text{LowNibble}$$

#### OBJECT DESCRIPTION

INDEX	600Ch
Name	pick_insertion
Object Code	Array
Data Type	Unsigned8
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to 05h
Default Value	05h

Sub-Index	01h
Description	pick_1
Entry Category	Mandatory
Access	wo
PDO Mapping	Default
Value Range	See definitions above
Default Value	00h

to

Sub-Index	05h
Description	pick_5
Entry Category	Mandatory
Access	wo
PDO Mapping	Default
Value Range	See definitions above
Default Value	00h



**5.2.14 Object 600Dh: digital outputs**

This object provides 8 x 8 digital output lines. The following value definitions shall apply:

0 = output switched off

1 = output switched on

**OBJECT DESCRIPTION**

INDEX	600Dh
Name	digital_outputs
Object Code	Array
Data Type	Unsigned8
Category	Mandatory

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to 08h
Default Value	No

Sub-Index	01h
Description	output_group_1
Entry Category	Mandatory
Access	rw
PDO Mapping	Default
Value Range	See definitions above
Default Value	00h

Sub-Index	02h
Description	output_group_2
Entry Category	Optional
Access	rw
PDO Mapping	Optional
Value Range	See definitions above
Default Value	00h

to

Sub-Index	08h
Description	output_group_8
Entry Category	Optional
Access	rw
PDO Mapping	Default
Value Range	See definitions above

Default Value	00h
---------------	-----

### 5.2.15 Object 600Eh: feeder command

This object allows controlling directly the feeders by the loom controller.

00h = non-operation mode (feeder reacts only on feeder commands and status requests)

01h = operation mode

02h = start (feeder runs with filling up speed)

03h = stop mode

04h = reset (feeder data are cleared and parameter reset)

05h = LED on

06h = LED off

07h = open the pin (valid only for pre-measuring feeders).

08h = close the pin (valid only for pre-measuring feeders).

09h to 5F = manufacturer-specific

60h to FFh = reserved

#### OBJECT DESCRIPTION

INDEX	600Eh
Name	feeder_command
Object Code	Array
Data Type	Unsigned8
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to FEh
Default Value	No

Sub-Index	01h
Description	feeder_1
Entry Category	Mandatory
Access	wo
PDO Mapping	No
Value Range	See definitions above
Default Value	No

Sub-Index	02h
Description	feeder_2
Entry Category	Optional
Access	wo
PDO Mapping	No
Value Range	See definitions above

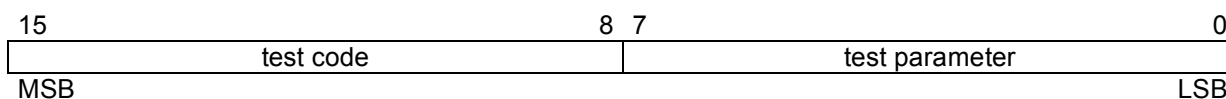
Default Value	No
---------------	----

to

Sub-Index	FEh
Description	feeder_254
Entry Category	Optional
Access	wo
PDO Mapping	No
Value Range	See definitions above
Default Value	No

### 5.2.16 Object 600Fh: feeder test

This object provides some feeder testing functionality. The corresponding test is executed only when the feeder is in operation mode. Only one test can be active each time. If a new test is received while a test is already in progress the current test is immediately stopped and the new test starts as soon as possible.



**Test code:** 0h = No Test: stop immediately any running test. Test parameter field can be any value and must be ignored.

1h = Motor Test: test parameter defines the motor speed in Hz with a range from 5 to 100 (Hz). A test parameter with a value of 0 means stop the motor test.

2h = Pin Test: test parameter defines the pin test frequency in Hz within the range from 1 to 20 (Hz). A test parameter with a value of 0 means stop the pin test.

3h = Strobo function: this test allows running the feeder in presence of the stroboscope light.

Test parameter meaning:

0x00 = Strobo function OFF.

0x01 = Strobo function ON.

4h to FF = reserved

**Test parameter:** See the definition of test code above.

#### OBJECT DESCRIPTION

INDEX	600Fh
Name	feeder_test
Object Code	Array
Data Type	Unsigned16
Category	Optional

#### ENTRY DESCRIPTION

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to FEh
Default Value	No

Sub-Index	01h
Description	feeder_1
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	See definitions above
Default Value	0h

Sub-Index	02h
Description	feeder_2
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	See definitions above
Default Value	00h

to

Sub-Index	FEh
Description	feeder_254
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	See definitions above
Default Value	00h

### 5.2.17 Object 6010h: feeder unwinding time

The feeder transmits this object to the loom controller by PDO service. This object is specific for pre-measuring feeders.

31	24 23	16 15
feeder selected	winding number	coil unwinding time
MSB		

Feeder selected: The number of feeder, which is inserting the weft from 01h to FEh. Note that on jet weaving machines only one weft feeder is selected each time.

Winding number: The number of winding which has been inserted. Allowed value range: 1 to 50.

Coil unwinding time: Time of the last inserted winding in 0,1 ms.  
The first pulse is the time from the trigger command to the first unwinding pulse. Allowed value range: 0 to 1000.

#### OBJECT DESCRIPTION

INDEX	6010h
Name	unwinding_time
Object Code	Variable
Data Type	Unsigned32
Category	Mandatory

#### ENTRY DESCRIPTION

Sub-Index	00h
Access	ro
PDO Mapping	Default
Value Range	See definitions above
Default Value	No

**5.2.18 Object 6011h: system feeder number assignment**

This object assigns a system feeder number to each feeder. The numbering is application-specific.

**OBJECT DESCRIPTION**

<b>INDEX</b>	<b>6011h</b>
Name	system_feeder_number_assignment
Object Code	Array
Data Type	Unsigned8
Category	Optional

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to FEh
Default Value	No

Sub-Index	01h
Description	feeder_1
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	Unsigned8
Default Value	01h

Sub-Index	02h
Description	feeder_2
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	Unsigned8
Default Value	02h

to

Sub-Index	FEh
Description	feeder_254
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	Unsigned8
Default Value	254h

**5.2.19 Object 6012h: feeder color assignment**

This object assigns one color to each feeder. The values are application-specific.

**OBJECT DESCRIPTION**

<b>INDEX</b>	<b>6012h</b>
Name	feeder_color_assignment
Object Code	Array
Data Type	Unsigned8
Category	Optional

**ENTRY DESCRIPTION**

Sub-Index	00h
Description	number_of_entries
Entry Category	Mandatory
Access	ro
PDO Mapping	No
Value Range	01h to FEh
Default Value	No

Sub-Index	01h
Description	feeder_1
Entry Category	Mandatory
Access	rw
PDO Mapping	No
Value Range	Unsigned8
Default Value	01h

Sub-Index	02h
Description	feeder_2
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	Unsigned8
Default Value	02h

to

Sub-Index	FEh
Description	feeder_254
Entry Category	Optional
Access	rw
PDO Mapping	No
Value Range	Unsigned8
Default Value	254h